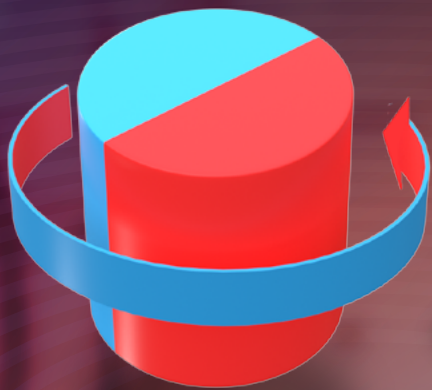


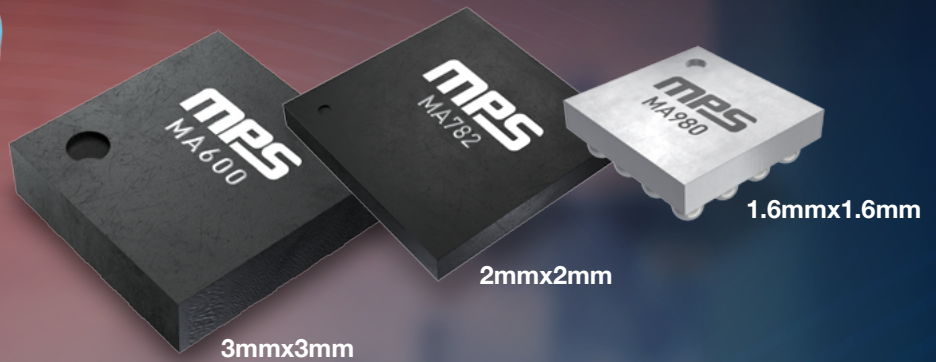


Sensor Solutions

Automotive | Industrial | Medical | Consumer



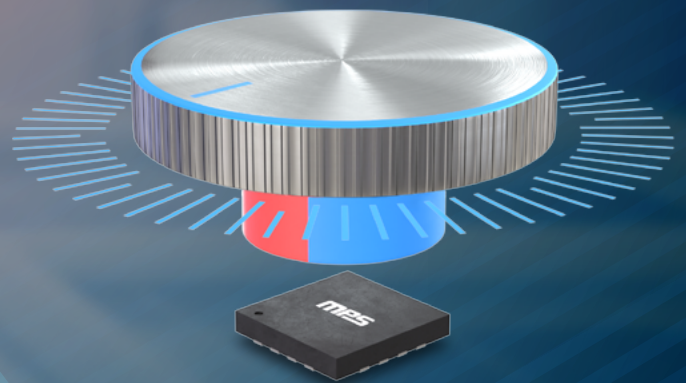
Position Sensing



Current Sensing




HMI



Quality Assurance & Reliability Commitment

The MPS Quality Assurance organization develops, coordinates, and champions strategic quality initiatives throughout MPS Inc., its foundries, and subcontractors. Its mission is to enable MPS to design, develop, manufacture, and deliver products to our customers with world-class quality and reliability that meet and exceed our customers' expectations.

MPS and Its Supplier Quality Systems and Certificates:

- ISO 9001:2008 (MPS)
- EU RoHS/HF/REACH Compliant (MPS)
- Sony Green Partner (MPS & Suppliers)
- TS16949 (Suppliers)
- ISO 14001 (Suppliers)
- Current Sensor UL Certification # CA-11398-UL 

Product Quality:

- Automotive Products Qualified per AEC-Q100 Standards
- Standard Products Qualified per JEDEC and Military Standards
- Reliability Failure Rate <10FIT
- Product Quality Level <1.0ppm

Quality Control and Monitoring:

- On-Site Foundry and Assembly Teams for Real-Time Actions
- Quarterly Supplier Quality Review and Annual Supplier Audit
- Short-Term Reliability Monitoring Test – Daily
- Long-Term Reliability Monitoring Test – Monthly
- Real-Time Engineering Actions on Monitored Failures
- Quarterly Reliability Monitoring Reports

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MagAlpha™, MagDiff™ & MagVector™ Contactless Magnetic Angle Sensors

Advantages of MagAlpha™ & MagDiff™ Sensors:

- Instantaneous, Absolute Angle Sensing
- High Resolution
- Factory-Calibrated Low Error (INL): <math><0.6^\circ</math>
- Less than - High Bandwidth Up to 21kHz
- Robust against Parasitic Stray Fields Exceeding 4kA/m DC
- Ideal for Battery-Powered Applications: 25µA Average Current
- Smallest Footprint: WLCSP (1.6mmx1.6mm) and UTQFN (2mmx2mm)
- Flexible Sensor Location: End-of-Shaft (On-Axis) or Side-Shaft (Off-Axis)

MagAlpha™ and MagDiff™ sensors utilize an array of Hall plates that are sampled successively at very high speeds in such a way that the signal phase represents the angle to be measured. The “phase-to-digital” SpinAxis™ technique captures the angle instantaneously every 1µs without the need for traditional analog-to-digital conversion or arc tangent calculation. This means that the sensor is able to operate across a wider magnetic field range (typically 30mT to 150mT), giving greater flexibility and tolerance for magnet positioning.

The MPS MagDiff™ family is ideal for applications that require stray-field immunity, such as motor control with other motors in close proximity. The angle is extracted from the difference of the magnetic field at several locations on the sensor IC. This differential method eliminates the contribution of parasitic magnetic fields, and is suitable for sensors positioned at the end-of-shaft with a simple target magnet.

Side-Shaft Capability

MagAlpha™ sensors support both end-of-shaft and side-of-shaft topologies. At end-of-shaft, the sensor is placed directly below the magnet connected to the rotating shaft. This topology offers the best performance, but is not always mechanically convenient because the end of a rotating shaft may not be accessible. For example, in a motor, it may be hidden by the shaft bearing, or driving into a gearbox. (see **Figure 1**).

The MagVector™ is our third type of magnetic position sensor. It is different than the MagAlpha™ and MagDiff™ in that it detects the direction and strength of a 3-dimensional (B_x, B_y, B_z) magnetic field and provides the digitized component data to the MCU via an SPI or I²C interface. Common applications for 3D sensing include power-meter tamper protection, joysticks, and gaming applications.

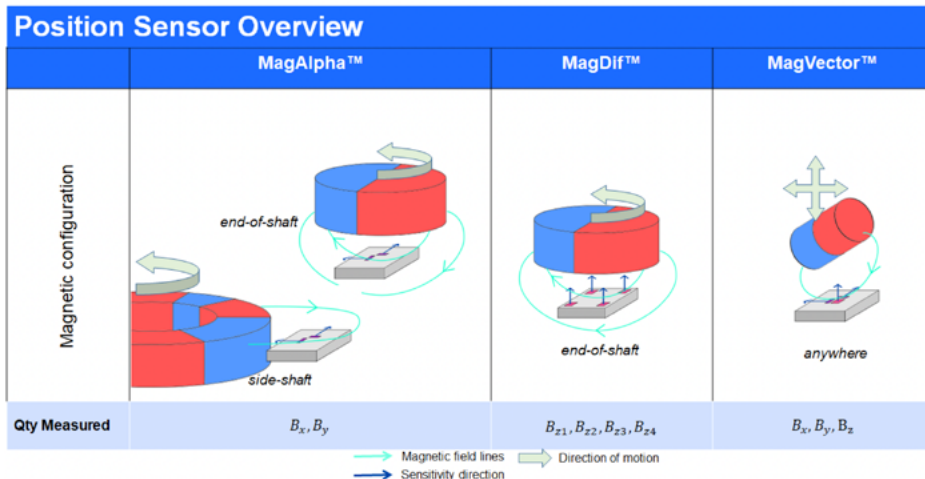


Figure 1: Magnet and Sensor Positioning

Current Sensors

Advantages of MPS Sensors:

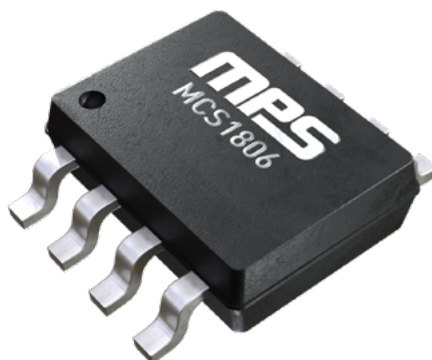
- Complete Isolated Current Sensors in SOIC-8 or WSOIC-10/16 packages
- Ultra-Small QFN-12 (3mmx3mm) for Non-Isolated Applications
- Lowest Primary Conductor Resistance for Higher Peak and Smaller Package
- Wide Current-Sensing Range from $\pm 5A$ to $\pm 400A$, AC or DC
- $\pm 2.5\%$ Accuracy over Temp, Factory-Trimmed
- Immune to Stray Magnetic Fields via Differential Sensing
- No Magnetic Hysteresys
- No Magnetic Hysteresis

MPS current sensors integrate galvanic isolation, high-voltage continuous operation, and high-current sensing into a small, industry-standard SOIC-8 or WSOIC-10/16 package. Our current sensors utilize an array of differential, linear Hall sensors that pick up the target induced magnetic field from the primary conductor while rejecting unwanted stray fields. This makes our current sensors ideal for use in magnetically noisy environments. In addition, the low resistance of the integrated conductor results in improved efficiency and reduced power loss compared to a traditional shunt resistor solution.

The primary conducting leads are electrically isolated from the sensor leads on the secondary side, producing a sensor with a high isolation voltage and working voltage. This makes our current sensors ideal for high-side current sensing without the need for expensive, large-footprint optical or inductive isolation alternatives.



MCS1823

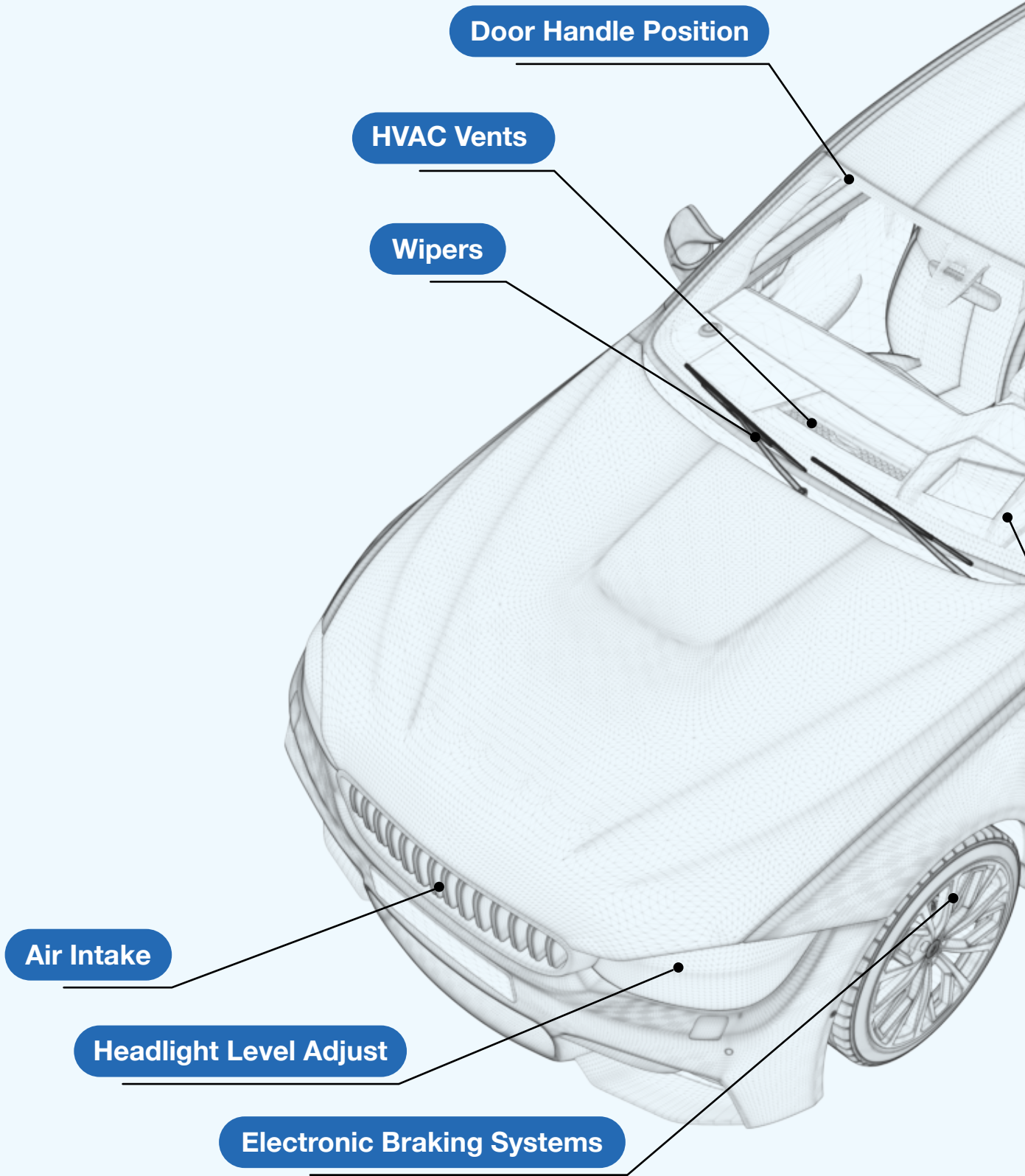


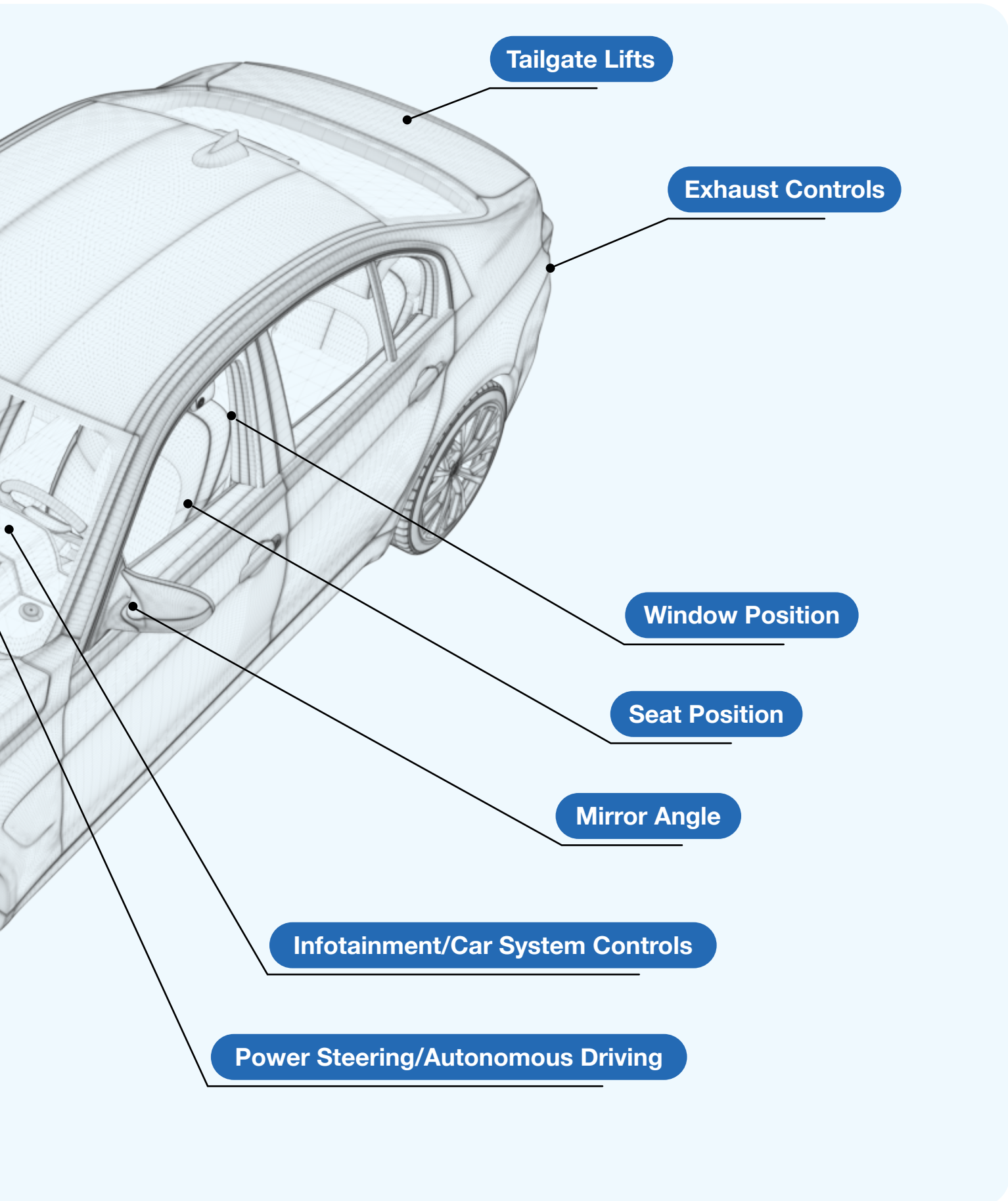
MCS1805/6



MCS1810/12

Sensors for Motor Position/Speed Control & Current Sensors





Tailgate Lifts

Exhaust Controls

Window Position

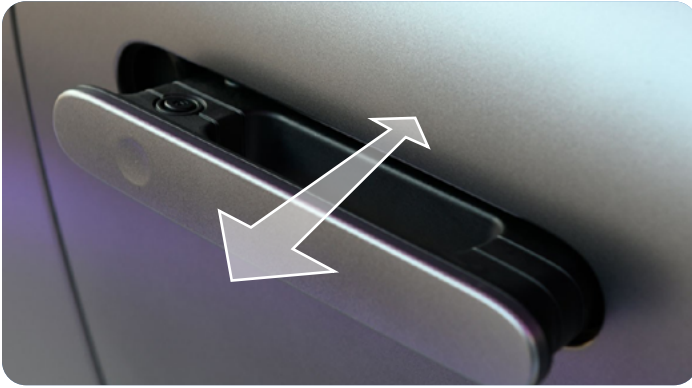
Seat Position

Mirror Angle

Infotainment/Car System Controls

Power Steering/Autonomous Driving

Body Electronics

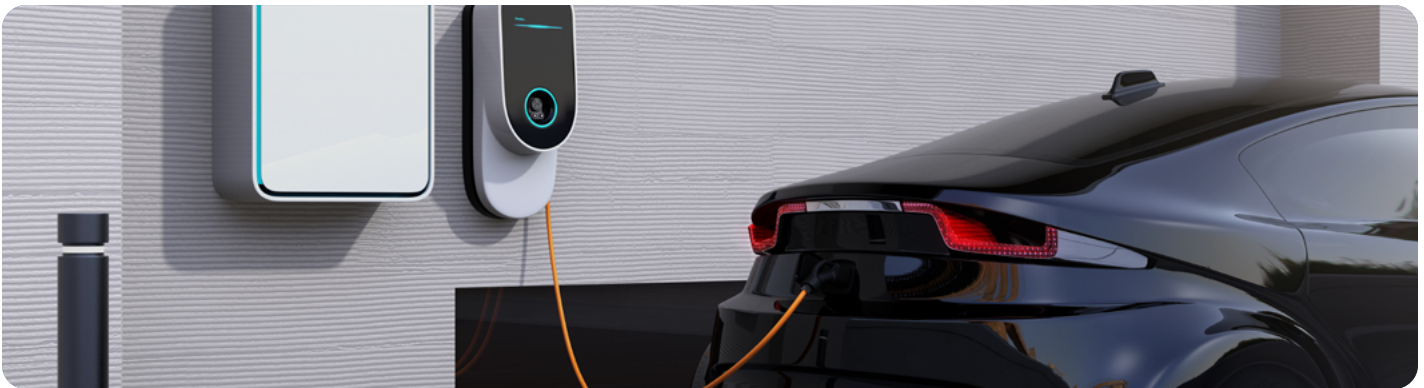


- Retracting Door Handles
- Tailgate Lifts
- Suspension Sensors



- Wiper Motors
- Spoiler Actuation

Power Management



Precision, High-Current Sensing and Control:

- Wallbox Chargers
- Qi Chargers
- Power Monitoring Systems

Thermal Management



- Fluid Pumps
- Air-Grill Shutters
- Cooling Fan Modules

Interior Cabin Control & Car Audio



- Contactless Infotainment Consoles
- Audio Amplifier Current-Sensing
- Contactless Gearshift Control



- Seat Position Motor Control
- Sunroof Motor Control

Electronic Power Steering (EPS)

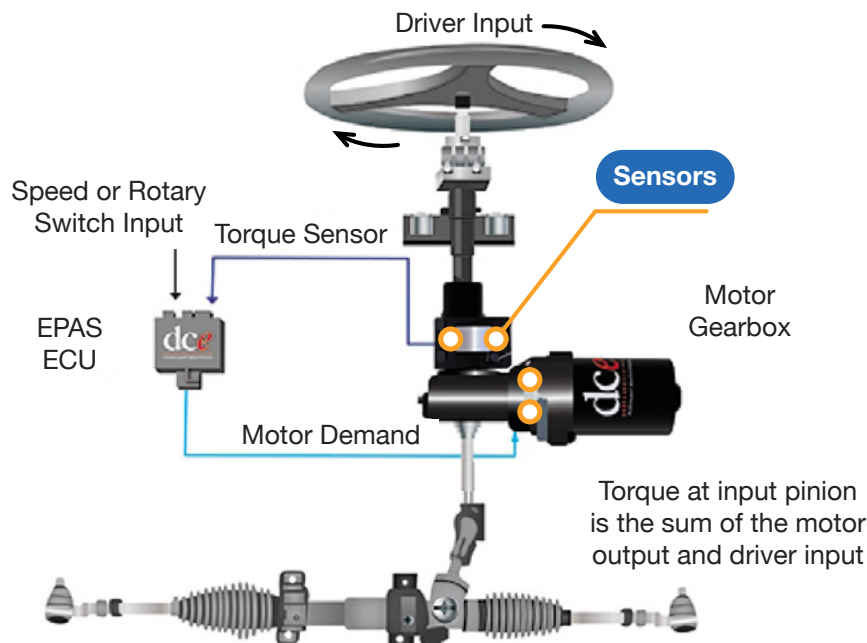
Replace Optical Sensors in Automotive Power-Assisted Steering (PAS)

MAQ600, MAQ473, and MAQ79010FS

- Cost-Effective, Contactless Alternative to Optical Sensing
- AEC-Q100 Grade 1 Qualified
- Wide Operating Temperature Range: -40°C to +150°C

MAQ79010FS

- Differential Sensing, Immune to Stray Magnetic Fields in Excess of 4kA/m DC
- ASIL-B Compliant with Functional Safety



Automotive Product Selector Guide

Integrated Current Sensors

| | Part Number | Current Range (A) | V _{CC} (V) | Over-Temperature Accuracy | Temp Range (°C) | Isolation Voltage (V _{RMS}) | Working Voltage (V _{RMS}) | Working Voltage for Basic Isolation (V _{RMS}) | Bandwidth (kHz) | Over-Current Detection for Reinforced Isolation (V _{RMS}) | Voltage Reference | Primary Conductor Resistance | UL Certification | Package | Notes |
|---|-------------|---|---------------------|---------------------------|-----------------|---------------------------------------|-------------------------------------|---|-----------------|---|-------------------|------------------------------|------------------|--------------|--|
| N | MCQ1805 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 3000 | 500 | - | 100 | ✓ | - | 0.9 | ✓ + TUV | SOIC-8 | AEC-Q100, coreless, ratiometric analog output, immune to external magnetic field gradients |
| | MCQ1806 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 3000 | 500 | - | 100 | - | - | 0.9 | ✓ | SOIC-8 | AEC-Q100, coreless, ratiometric analog output |
| S | MCQ1810 | ±10, ±20, ±30, ±40, ±50, ±65, ±80, ±100 | 3.3, 5 | 2% | -40 to +150 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.3 | Planned | SOIC-10W | AEC-Q100, coreless, zero current reference, 0.3mΩ low primary conductor resistance, bi- or unidirectional sensing, ratiometric or absolute analog output, OCD with 1μs response time |
| S | MCQ1812 | ±10, ±20, ±30, ±40, ±50, ±65, ±80 | 3.3, 5 | 2% | -40 to +150 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.45 | Planned | SOIC-16W | AEC-Q100, coreless, zero current reference, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1μs response time |
| S | MCQ1814 | ±5, ±10, ±20, ±30, ±40, ±50, ±65, ±80 | 3.3, 5 | 2% | -40 to +150 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.45 | Planned | SOIC-16W | AEC-Q100, coreless, zero current reference, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1μs response time |
| | MCQ1823 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 100 | 100 | - | 120 | ✓ | - | 0.6 | ✓ | QFN-12 (3x3) | AEC-Q100, coreless, bi- or unidirectional sensing, ratiometric or absolute analog output, immune to external magnetic field gradients |
| S | MCQ1880 | ±50, ±100, ±150, ±200 | 3.3, 5 | 2% | -40 to +150 | 100 | 100 | - | 350 | - | - | 0.2 | - | PSOF-7 | AEC-Q100, bi- or unidirectional sensing, 0.2mΩ primary conductor resistance, high precision, ratiometric or absolute analog output |
| P | MCQ1809 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2% | -40 to +125 | 3000 | 550 | - | 350 | ✓ | - | 0.5 | - | SOIC-8 | AEC-Q100, coreless, ratiometric analog output |



MagAlpha™ Magnetic Position Sensors

| | Part Number | ±30° Resolution | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Cutoff Frequency (mT) | Latency at Constant Speed (Hz) | Magnetic Field Detection | Temperature Range (°C) | Package | Wettable Flanks | Notes |
|---|-------------|------------------|-------------------------------------|--------------------|----------------------|--------------------|-----------------------|--------------------------------|--------------------------|------------------------|---------|--|-------|
| | MAQ430 | 12-Bit | SPI, UVW, ABZ 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | - | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100 | |
| | MAQ470 | 12-Bit | SPI, SSI, PWM, ABZ 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | ✓ | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100 | |
| | MAQ473 | 10-Bit to 14-Bit | SPI, SSI, PWM, ABZ 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 23 to 6k | 8 | ✓ | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100, prog. filter | |
| | MAQ800 | 8-Bit | SPI, SSI 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | ✓ | -40 to +125 | QFN-16 (3x3) | ✓ | Optimized for automotive HMI applications, SSI output | |
| | MAQ820 | 8-Bit | SPI, ABZ 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | ✓ | -40 to +125 | QFN-16 (3x3) | ✓ | Optimized for automotive HMI applications, SSI output | |
| | MAQ850 | 8-Bit | SPI, PWM 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | ✓ | -40 to +125 | QFN-16 (3x3) | ✓ | Optimized for automotive HMI applications, SSI output | |
| N | MAQ600A | 12-Bit to 15-Bit | SPI, ABZ, PWM, UVW, SSI 3 to 3.6 | 7.5 | 20+ (No Upper Limit) | 75 to 17k | 0 | ✓ | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100, TMR front-end, high accuracy and BW, 0.6° INL (<0.1° INL through user calibration w/ 32-word lookup table) | |

MagDiff™ Magnetic Position Sensors with Stray Field Immunity

| | Part Number | ±3σ Resolution | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Cutoff Frequency (Hz) | Latency at Constant Speed (μs) | Magnetic Field Detection Temperature Range (°C) | Package | Wettable Flanks | Notes | |
|---|-------------|--------------------|--|--------------------|---------------------|---------------------|-----------------------|--------------------------------|---|-------------|-----------------|-------|---|
| S | MAQ79010 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, SENT, ABZ | 3.3V, 5V | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | ✓ | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100, ASIL-B compliant, robust against parasitic stray fields >4kA/m DC, or 5mT |
| P | MAQ79016 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, SENT, ABZ | Up to 26V | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | ✓ | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100, ASIL-B compliant, 26V with reverse polarity protection, robust against parasitic stray fields >4kA/m DC, or 5mT |
| S | MAQ900 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, SENT, ABZ | 3.3V, 5V | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | ✓ | -40 to +150 | QFN-16 (3x3) | ✓ | AEC-Q100, robust against parasitic stray fields >4kA/m DC, or 5mT |
| P | MAQ79020 | 12-Bit to 14.5-Bit | ABZ, PWM, SPI, I ² C, SSI, UVW | 3.3V, 5V | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | ✓ | -40 to +150 | QFN-32 (5x5) | ✓ | AEC-Q100, ASIL-D compliant w/ functional safety, robust against parasitic stray fields >4kA/m DC or 5mT, wettable flanks |

MagVector™ 3D Magnetic Position Sensors

| | Part Number | Data Length | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Conversion Time (μs) | Temperature Range (°C) | Package | Notes |
|---|-------------|-------------|-----------------------|--------------------|---------------------|--------------------|----------------------|------------------------|----------|---|
| P | MVQ310 | 12-Bit | I ² C, SPI | 3.3 | 25nA to 2.5 | ±125 or ±250 | 40 | -40 to +150 | TSOT23-6 | AEC-Q100, digital component output, selectable operating power modes and sensing axis |

Safety & Security



- Access Control
- Automated Doors
- Smart Door Locks
- Elevators and Escalators
- Fire Prevention

Power Management



- Solar Inverters
- Power Monitoring



- Power Access
- Light Monitoring

Solar Inverters



Maintain Maximum Power Point Tracking

MCS1823, MCS1805, and MCS1806

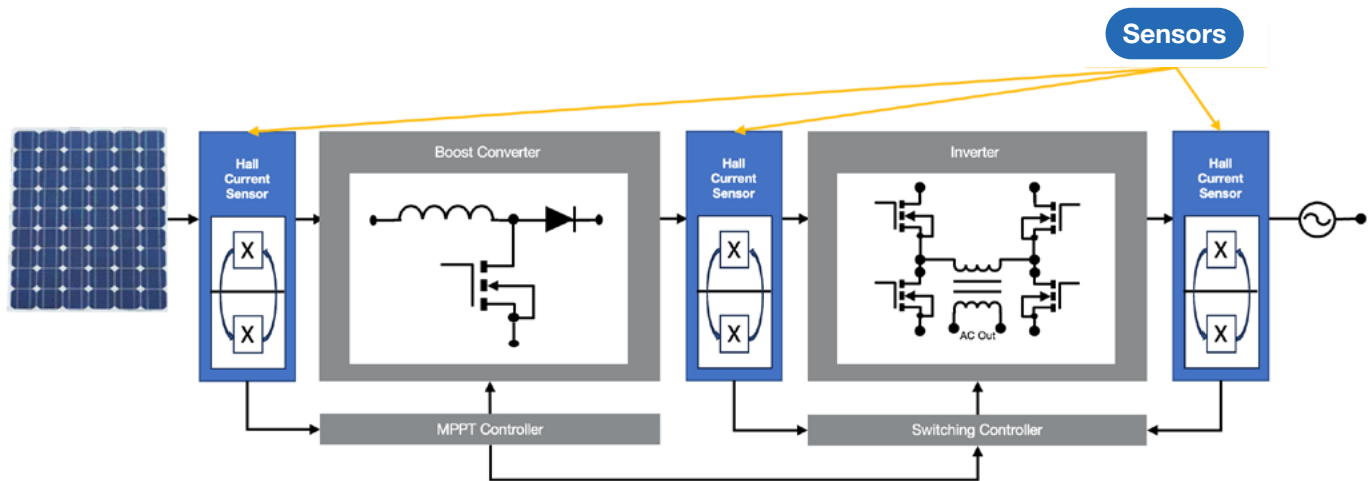
- Accurate High-Side or Low-Side Current Sensing
- Up to 3kV_{RMS} High Isolation from Line Voltage
- Fast Over-Current Detection Flag <1μs
- UL Certified

Boost Modules

- Accurate Current Sampling to Detect the Power Output from the PV Cells
- Control the PWM Duty Cycle to Increase or Decrease the Downstream Impedance

Inverter Stage

- Accurately Track Current Phase to Match Line Current
- Accurately Track Power Delivered to the Line



Climate & Energy Efficiency

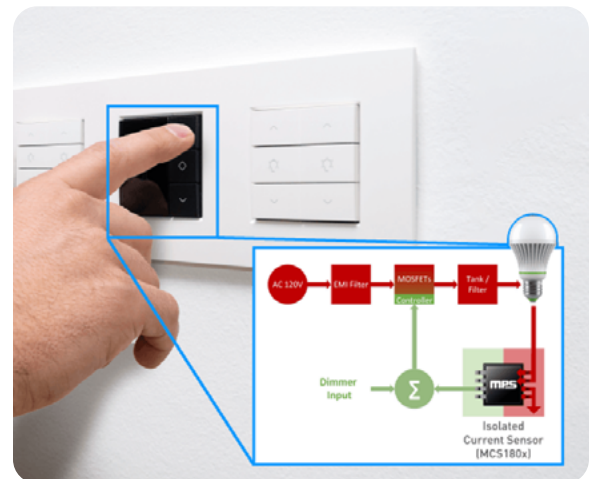


- Shutters and Blinds
- HVAC – Compressors, Blowers, Flow Control
- Climate Control – Thermostats
- Lighting Dimmer Control

Smart Lighting Dimmers

MCS1806

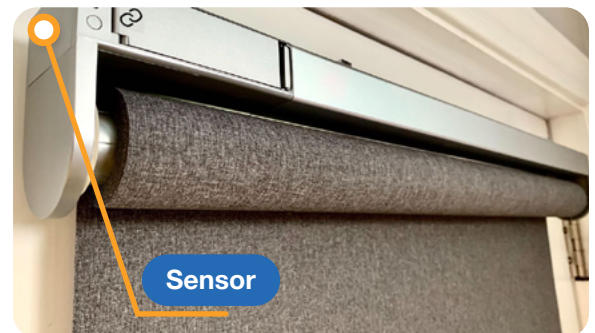
- Direct Sensing in Industry-Standard SOIC-8 Package
- Wide $\pm 5A$ to $\pm 50A$ Sensing Range
- Low $0.9m\Omega$ Primary Conductor Resistance
- $3000V_{RMS}$ Isolation



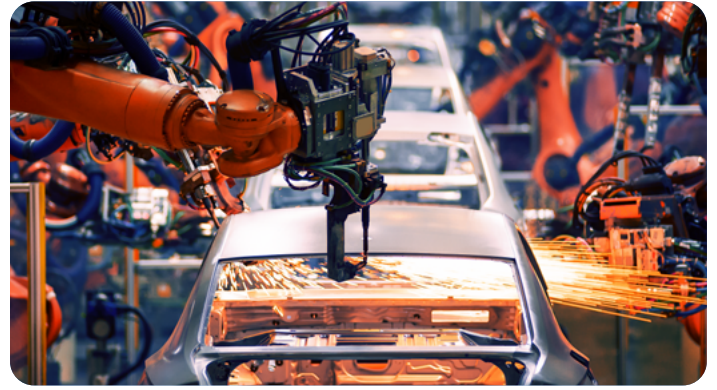
Smart Shades

MA732, MA330, MA735, MA736, and MA782

- Motor Commutation and/or Position Feedback
- Provides Absolute Feedback
- Operates with a Low-Cost Magnet
- Works with All Types of Motors
- Can Be Operated at Side-Shaft or End-of-Shaft Locations
- Ideal for Space-Constrained Applications
 - MA735, MA736, MA782: UTQFN (2mmx2mm) Package
- MA782 Is Ideal for Battery-Powered Applications
 - Includes Wake-Up on Angle Detection
 - $0.5\mu A$ Standby Current



Industrial Automation



Precision Robotic Joint Control

MA600

- Factory-Calibrated: 0.6° Error (INL) over Temp
- <math><0.1^\circ</math> Error (INL) after User Calibration with On-Board Chip Look-Up Table
- 12-Bit to 15-Bit Noise-Free Resolution
- 17kHz Bandwidth
- Zero Latency to Minimize Speed Errors

MA900

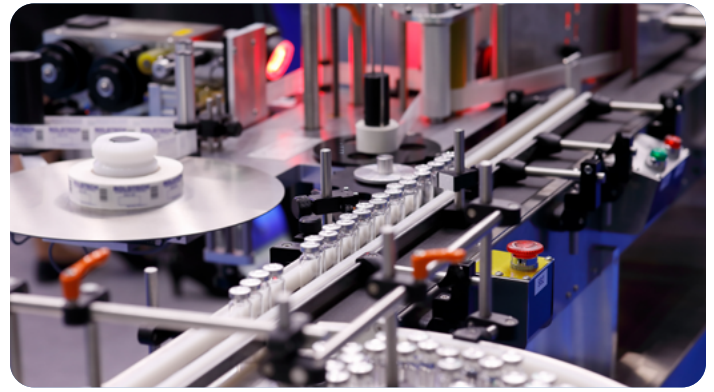
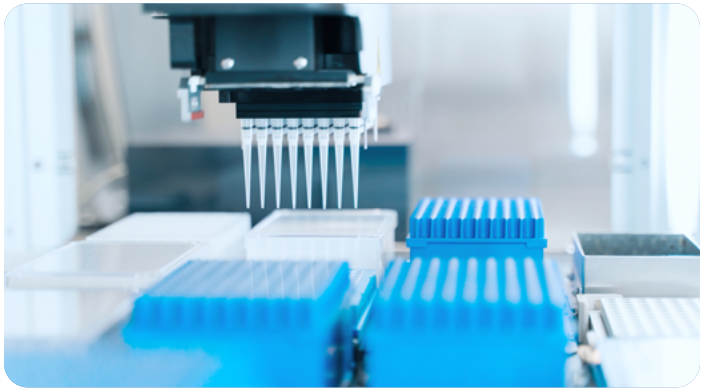
- Differential Sensing, Immune to Stray Magnetic Fields in Excess of 4kA/m DC
- 10-Bit to 14.5-Bit Noise-Free Resolution
- Available in a Tiny QFN-16 (3mmx3mm) Package

Cost-Effective Solution for Managing:

- High-Speed Torque
- Position
- Speed Control

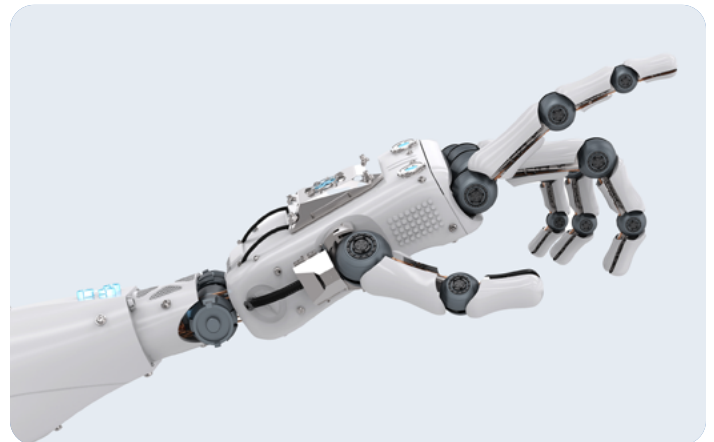
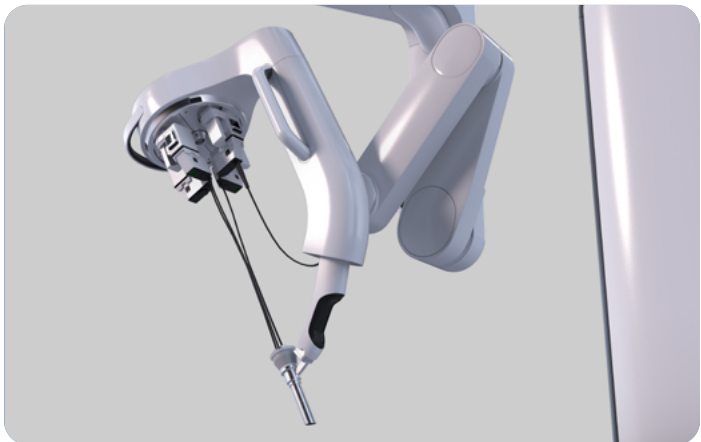


Lab Automation



- Robot Control
- Probe Processing
- Pump Motor Control
 - Infusion Pumps
 - Insulin Pumps

Humanoid & Surgical Robotics



- Automated and Remote Surgical Robots
- Dental Processing

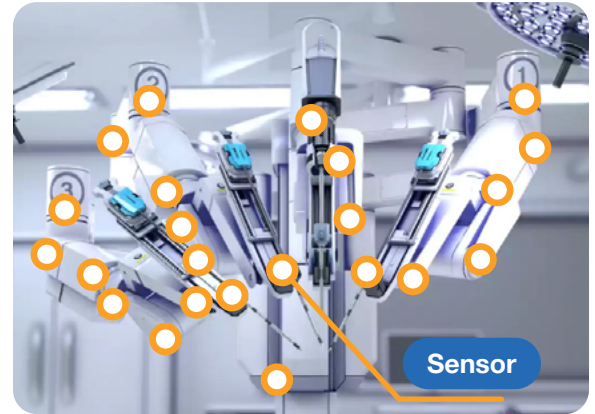
Surgical Robotics

MA600

- Factory-Calibrated: 0.6° Error (INL) over Temp
- <math><0.1^\circ</math> Error (INL) after User Calibration with On-Board Chip Look-Up Table
- 12-Bit to 15-Bit Noise-Free Resolution
- 21kHz Bandwidth
- Zero Latency to Minimize Speed Errors

MA900

- Differential Sensing, Immune to Stray Magnetic Fields in Excess of 4kA/m DC
- 10-Bit to 14.5-Bit Noise-Free Resolution
- Available in a Tiny QFN-16 (3mmx3mm) Package



Cost-Effective Solution for Managing:

- High-Speed Torque
- Position
- Speed Control

Insulin Pumps



Accuracy and Reliability in Tiny Form Factor

MA980

- 9-Bit To 13-Bit Absolute Resolution
- Differential Sensing Rejects Stray Fields
- μ Power Operation through Duty Cycle Control
- CSP-16 (1.6mmx1.6mm) Package Is Ideal for Space-Constrained Applications

Mobile Phones, Laptops, and VR Headsets



- Foldable Mobile Flip-Phone Angle Management
- Foldable Tablet Angle Sensing
- Precision Open/Close Angle Management
- HMI Contactless Knobs & Buttons

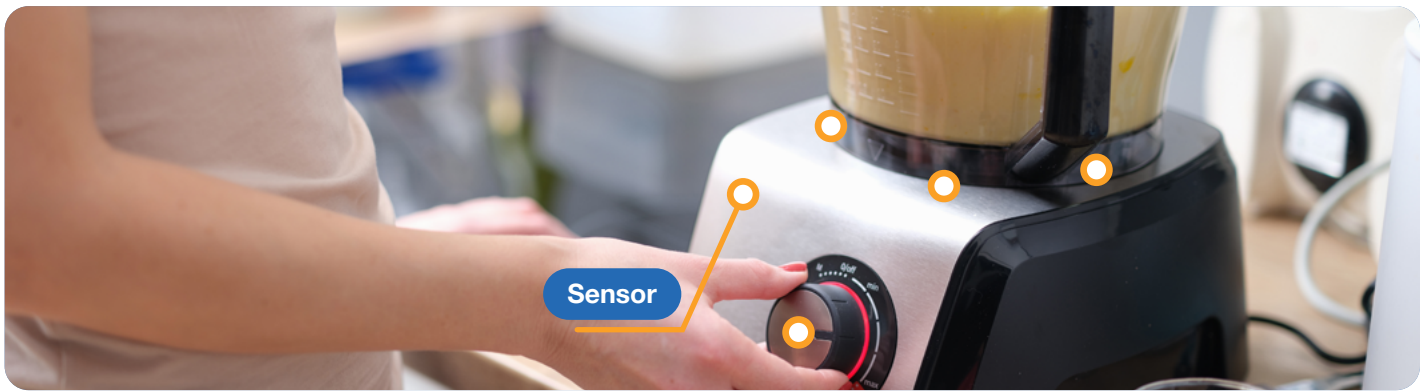
No-Bezel Laptops and Foldable Phones

MA782 or MA980

- Smallest Open/Close-Detection Solution
- Helps Minimize or Eliminate Bezel
- Can Be Placed in the Folding Axis
- Smallest WLCSP Package (1.6mmx1.6mm)
- Lowest Power: 25 μ A Duty Cycle
- Wake-On-Change Angle Detection
- Very Small (<1mmx1mm) Magnet
- Provides Absolute Angle Output without MCU Support



Kitchen Appliances/Mixers with Cooking Options



Main Motor Position Detection

MA732, MA735, MA736, and MA900

- Motor Commutation and/or Position Feedback
- Ideal for Space-Constraint Applications
 - MA735, MA736: UTQFN (2mmx2mm) Package
- Differential Sensing Rejects Stray Fields
 - MA900: End-of-Shaft Only

Secure Lid Closure Detection

MV300, MV310

- Senses Position of Magnets in Lid
- Flexible I²C or SPI Interface

Control and Menu Buttons

MA800

- Contactless Sensing for Long Life with No Wear
- 8-Bit Resolution Absolute Angle Encoder
- Push and Pull Detection with Configurable Thresholds

Current Sensing

(Heating, Motor Control, Power Supplies)

MCS1806, MCS1810/12

- Complete Isolated Current Sensor
- Wide Sensing Range
 - $\pm 5A$ to $\pm 160A$, AC or DC

E-Bikes & Scooters



- BLDC Motors – Smaller, Lighter, Increased Reliability
- Enables Highest Power Density
- Provides Absolute Angle, Position, and Torque

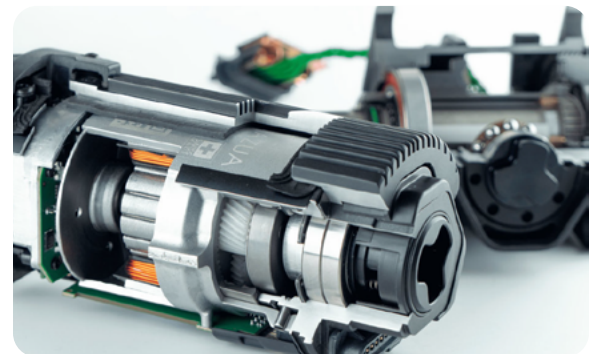
Flexible Interface:

- SPI Commutation for UVW Commutation
- ABZ Speed Control

Sensors for E-Bike Ultra-Small BLDC Motors

MA302

- Speed, Torque, and Absolute Position Control
- Smallest QFN (3mmx3mm) Package
- No Customer Calibration Required
- Factory Calibrated
- On-Chip Non-Volatile Memory (NVM)
- Wide -40°C to +125°C Operating Temp Range
- Flexible Interface
 - SPI for Digital Angle Readout and Sensor Configuration
 - ABZ/UVW for Motor Control, Commutation, and Incremental Output
 - No Firmware Changes Required when Replacing Optical Encoders; ABZ Output Is Compatible with Optical Outputs



Consumer & Industrial Product Selector Guide

Integrated Current Sensors

| | Part Number | Current Range (A) | V _{CC} (V) | Over-Temp. Accuracy | Temperature Range (°C) | Isolation Voltage (V _{RMS}) | Working Voltage (V _{RMS}) | Working Voltage for Basic (V _{RMS}) | Working Voltage for Reinforced Isolation (V _{RMS}) | Bandwidth (kHz) | Over-Current Detection (OCD) | Primary Conductor Resistance (mΩ) | UL Certification | Package | Notes |
|---|-------------|---|---------------------|---------------------|------------------------|---------------------------------------|-------------------------------------|---|--|-----------------|------------------------------|-----------------------------------|------------------|--------------|--|
| | MCS1800 | ±12.5, ±25 | 3.3 | 3% | -40 to +125 | 1000 | 200 | - | 100 | - | - | 1.2 | - | SOIC-8 | Coreless, ratiometric analog output |
| | MCS1801 | ±12.5, ±25 | 5 | 3% | -40 to +125 | 1000 | 200 | - | 100 | - | - | 1.2 | - | SOIC-8 | Coreless, ratiometric analog output |
| | MCS1802 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3 | 2.5% | -40 to +125 | 2200 | 250 | - | 100 | - | - | 0.9 | ✓ | SOIC-8 | Coreless, ratiometric analog output |
| | MCS1803 | ±5, ±10, ±20, ±30, ±40, ±50 | 5 | 2.5% | -40 to +125 | 2200 | 250 | - | 100 | - | - | 0.9 | ✓ | SOIC-8 | Coreless, ratiometric analog output |
| | MCS1805 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 3000 | 500 | - | 100 | ✓ | - | 0.9 | ✓ + TUV | SOIC-8 | Coreless, ratiometric analog output, immune to external magnetic field gradients |
| | MCS1806 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 3000 | 500 | - | 100 | - | - | 0.9 | ✓ | SOIC-8 | Coreless, ratiometric analog output |
| S | MCS1810 | ±10, ±20, ±30, ±40, ±50, ±65, ±80, ±100 | 3.3, 5 | 2% | -40 to +125 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.3 | Planned | SOIC-10W | Coreless, zero current reference, low primary conductor resistance, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1µs response time |
| S | MCS1812 | ±10, ±20, ±30, ±40, ±50, ±65, ±80, ±100 | 3.3, 5 | 2% | -40 to +125 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.45 | Planned | SOIC-16W | Coreless, zero current reference, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1µs response time |
| S | MCS1814 | ±10, ±20, ±30, ±40, ±50, ±65, ±80, ±100 | 3.3, 5 | 2% | -40 to +125 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.45 | Planned | SOIC-16W | Coreless, zero current reference, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1µs response time |
| | MCS1823 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 100 | 100 | - | 120 | ✓ | - | 0.6 | ✓ | QFN-12 (3x3) | Coreless, bi- or unidirectional sensing, ratiometric or absolute analog output, immune to external magnetic field gradients |
| | MCS1826 | ±15.5, ±31 | 3.3 to 5 | 3% | -40 to +125 | 100 | 100 | - | 120 | ✓ | - | 0.6 | ✓ | QFN-12 (3x3) | Coreless, bidirectional sensing, ratiometric analog output, immune to external magnetic field gradients |
| S | MCS1880 | ±50, ±100, ±150, ±200 | 3.3, 5 | 2% | -40 to +125 | 100 | 100 | - | 350 | - | - | 0.2 | - | PSOF-7 | Bi- or unidirectional sensing, 0.2mΩ primary conductor resistance, high precision, ratiometric or absolute analog output |
| P | MCS1809 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2% | -40 to +125 | 3000 | 550 | - | 350 | ✓ | - | 0.5 | - | SOIC-8 | Coreless, ratiometric analog output |

| | Part Number | Current Range (A) | V _{CC} (V) | Over-Temp. Accuracy | Temperature Range (°C) | Isolation Voltage (V _{RMS}) | Working Voltage (V _{RMS}) | Working Voltage for Basic (V _{RMS}) | Working Voltage for Reinforced Isolation (V _{RMS}) | Bandwidth (kHz) | Over-Current Detection Voltage Reference | Primary Conductor Resistance (mΩ) | UL Certification | Package | Notes |
|---|-------------|---|---------------------|---------------------|------------------------|---------------------------------------|-------------------------------------|---|--|-----------------|--|-----------------------------------|------------------|--------------|--|
| N | MCQ1805 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 3000 | 500 | - | 100 | ✓ | - | 0.9 | ✓ + TUV | SOIC-8 | AEC-Q100, coreless, ratiometric analog output, immune to external magnetic field gradients |
| | MCQ1806 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 3000 | 500 | - | 100 | - | - | 0.9 | ✓ | SOIC-8 | AEC-Q100, coreless, ratiometric analog output |
| S | MCQ1810 | ±10, ±20, ±30, ±40, ±50, ±65, ±80, ±100 | 3.3, 5 | 2% | -40 to +150 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.3 | Planned | SOIC-10W | AEC-Q100, coreless, zero current reference, 0.3mΩ low primary conductor resistance, bi- or unidirectional sensing, ratiometric or absolute analog output, OCD with 1μs response time |
| S | MCQ1812 | ±10, ±20, ±30, ±40, ±50, ±65, ±80 | 3.3, 5 | 2% | -40 to +150 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.45 | Planned | SOIC-16W | AEC-Q100, coreless, zero current reference, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1μs response time |
| S | MCQ1814 | ±5, ±10, ±20, ±30, ±40, ±50, ±65, ±80 | 3.3, 5 | 2% | -40 to +150 | 5000 | 1100 | 560 | 350 | ✓ | ✓ | 0.45 | Planned | SOIC-16W | AEC-Q100, coreless, zero current reference, bi- or unidirectional sensing, ratiometric or absolute analog output, prog. OCD with 1μs response time |
| | MCQ1823 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2.5% | -40 to +125 | 100 | 100 | - | 120 | ✓ | - | 0.6 | ✓ | QFN-12 (3x3) | AEC-Q100, coreless, bi- or unidirectional sensing, ratiometric or absolute analog output, immune to external magnetic field gradients |
| S | MCQ1880 | ±50, ±100, ±150, ±200 | 3.3, 5 | 2% | -40 to +150 | 100 | 100 | - | 350 | - | - | 0.2 | - | PSOF-7 | AEC-Q100, bi- or unidirectional sensing, 0.2mΩ primary conductor resistance, high precision, ratiometric or absolute analog output |
| P | MCQ1809 | ±5, ±10, ±20, ±30, ±40, ±50 | 3.3, 5 | 2% | -40 to +125 | 3000 | 550 | - | 350 | ✓ | - | 0.5 | - | SOIC-8 | AEC-Q100, coreless, ratiometric analog output |

MagVector™ 3D Magnetic Position Sensors

| | Part Number | Data Length | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Conversion Time (µs) | Temperature Range (°C) | Package | Notes |
|----------|---------------|-------------|-----------------------|--------------------|---------------------|--------------------|----------------------|------------------------|----------|---|
| | MV300 | 12-Bit | I ² C, SPI | 3.3 | 10nA to 2.5 | ±50 or ±180 | 40 | -40 to +125 | TSOT23-6 | Digital component output, selectable operating power modes |
| P | MV310 | 12-Bit | I ² C, SPI | 3.3 | 25nA to 2.3 | ±125 or ±250 | 40 | -40 to +125 | TSOT23-6 | Digital component output, selectable operating power modes and sensing axis |
| P | MVQ310 | 12-Bit | I ² C, SPI | 3.3 | 25nA to 2.3 | ±125 or ±250 | 40 | -40 to +150 | TSOT23-6 | AEC-Q100, digital component output, selectable operating power modes and sensing axis |

MagDiff™ Magnetic Position Sensors with Stray Field Immunity

| | Part Number | ±3σ Resolution | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Cutoff Frequency (Hz) | Latency at Constant Speed (µs) | Temperature Range (°C) | Package | Notes |
|----------|-----------------|--------------------|--|--------------------|----------------------|---------------------|-----------------------|--------------------------------|------------------------|-----------------|--|
| S | MA900 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, ABZ | 3.3, 5 | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | -40 to +125 | QFN-16 (3x3) | Robust against parasitic stray fields exceeding 4kA/m DC, or 5mT |
| S | MA980 | 9-Bit to 13-Bit | SPI | 3.3, 5 | 25µA (256µs On Time) | 8+ (No Upper Limit) | 5 to 160k | 5 to 4100 | -40 to +125 | WLCSP (1.6x1.6) | Micropower, smallest footprint, robust against parasitic stray fields |
| S | MAQ79010 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, SENT, ABZ | 3.3, 5 | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | -40 to +150 | QFN-16 (3x3) | AEC-Q100, ASIL-B compliant with functional safety, robust against parasitic stray fields exceeding 4kA/m DC, or 5mT, wettable flanks |
| P | MAQ79016 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, SENT, ABZ | Up to 26 | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | -40 to +150 | QFN-16 (3x3) | AEC-Q100, ASIL-B compliant with functional safety, 26V with reverse polarity protection, robust against parasitic stray fields >4kA/m DC, or 5mT |
| S | MAQ900 | 10-Bit to 14.5-Bit | SPI, SSI, I ² C, UVW, SENT, ABZ | 3.3, 5 | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | -40 to +150 | QFN-16 (3x3) | AEC-Q100, robust against parasitic stray fields >4kA/m DC, or 5mT |
| S | MAQ980 | 9-Bit to 13-Bit | SPI | 3.3, 5 | 25µA (256µs On Time) | 8+ (No Upper Limit) | 5 to 160k | 0 | -40 to +125 | UTQFN (2x2) | AEC-Q100, micropower, smallest footprint, robust against parasitic stray fields >4kA/m DC, or 5mT |
| P | MAQ79020 | 12-Bit to 14.5-Bit | ABZ, PWM, SPI, I ² C, SSI, UVW | 3.3, 5 | 12 | 8+ (No Upper Limit) | 12 to 100k | 0 | -40 to +150 | QFN-32 (5x5) | AEC-Q100, ASIL-D compliant w/ functional safety, robust against parasitic stray fields >4kA/m DC or 5mT, wettable flanks |

MagAlpha™ Magnetic Position Sensors

| Part Number | ±3σ Resolution | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Cutoff Frequency (Hz) | Latency at Constant Speed (μs) | Temperature Range (°C) | Package | Notes |
|-------------|-------------------|--------------------|--------------------|----------------------|----------------------|-----------------------|--------------------------------|------------------------|----------------|--|
| MA102 | 12-Bit | SPI, UVW | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | -40 to +125 | QFN-16 (3x3) | Motor commutation angle sensor, UVW multi-pole pair, differential outputs |
| MA302 | 12-Bit | SPI, UVW, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | -40 to +125 | QFN-16 (3x3) | Motor commutation angle sensor, 12-bit SPI output, ABZ & UVW incremental outputs |
| MA310 | 12-Bit | SPI, UVW, ABZ | 3 to 3.6 | 11.7 | 15+ (No Upper Limit) | 93 | 8 | -40 to +125 | QFN-16 (3x3) | Motor commutation angle sensor, 12-bit SPI output, low magnetic field |
| MA330 | 10-Bit to 14-Bit | SPI, UVW, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 23 to 6k | 8 | -40 to +125 | QFN-16 (3x3) | Motor commutation angle sensor, up to 14-bit SPI output, programmable filter |
| MA702 | 12-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | -40 to +125 | QFN-16 (3x3) | 12-bit SPI output, ABZ incremental & PWM outputs |
| MA704 | 10-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 2970 | 8 | -40 to +125 | QFN-16 (3x3) | 12-bit SPI output, high BW, ABZ incremental & PWM outputs |
| MA710 | 12-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 15+ (No Upper Limit) | 93 | 8 | -40 to +125 | QFN-16 (3x3) | 12-bit SPI output, low magnetic field, ABZ incremental & PWM outputs |
| MA730 | 14-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 40+ (No Upper Limit) | 23 | 8 | -40 to +125 | QFN-16 (3x3) | 14-bit SPI output, ABZ incremental & PWM outputs |
| MA732 | 10-Bit to 14-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 23 to 6k | 8 | -40 to +125 | QFN-16 (3x3) | Prog. filter, ABZ incremental & PWM outputs |
| MA734 | 8-Bit to 12.5-Bit | SPI | 3 to 3.6 | 11 | 30+ (No Upper Limit) | 95, 380, 95k | 3 | -40 to +125 | QFN-16 (3x3) | Prog. filter, low latency |
| MA735 | 9-Bit to 13-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 40+ (No Upper Limit) | 23 to 6k | 8 | -40 to +125 | UTQFN-14 (2x2) | Ultra-small footprint, prog. filter, ABZ incremental & PWM outputs |
| MA736 | 8-Bit to 12.5-Bit | SPI | 3 to 3.6 | 11 | 30+ (No Upper Limit) | 95, 380, 95k | 3 | -40 to +125 | UTQFN-14 (2x2) | Ultra-small footprint, prog. filter, low latency |
| MA780 | 8-Bit to 12-Bit | SPI | 3 to 3.6 | 50μA (512μs On Time) | 30+ (No Upper Limit) | 5 to 160k | 4 to 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for low-power, integrated wake-up and IRQ |
| MA782 | 8-Bit to 12-Bit | SPI | 3 to 3.6 | 50μA (512μs On Time) | 30+ (No Upper Limit) | 5 to 160k | 4 to 4000 | -40 to +125 | UTQFN-14 (2x2) | Micropower, ultra-small footprint, integrated wake-up and IRQ |
| MA800 | 8-Bit | SPI, SSI | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for HMI applications |
| MA820 | 8-Bit | SPI, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for HMI applications |
| MA850 | 8-Bit | SPI, PWM | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for HMI applications |

| Part Number | ±3σ Resolution | Interface | Supply Voltage (V) | Supply Current (mA) | Sensing Range (mT) | Cutoff Frequency (Hz) | Latency at Constant Speed (μs) | Temperature Range (°C) | Package | Notes |
|----------------|------------------|-------------------------|--------------------|---------------------|----------------------|-----------------------|--------------------------------|------------------------|--------------|--|
| MAQ430 | 12-Bit | SPI, UVW, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | -40 to +150 | QFN-16 (3x3) | AEC-Q100, wettable flanks |
| MAQ470 | 12-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 390 | 8 | -40 to +150 | QFN-16 (3x3) | AEC-Q100, wettable flanks |
| MAQ473 | 10-Bit to 14-Bit | SPI, SSI, PWM, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 23 to 6k | 8 | -40 to +150 | QFN-16 (3x3) | AEC-Q100, prog. filter, wettable flanks |
| MAQ800 | 8-Bit | SPI, SSI | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for automotive HMI applications, SSI output, wettable flanks |
| MAQ820 | 8-Bit | SPI, ABZ | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for automotive HMI applications, SSI output, wettable flanks |
| MAQ850 | 8-Bit | SPI, PWM | 3 to 3.6 | 11.7 | 30+ (No Upper Limit) | 90 | 4000 | -40 to +125 | QFN-16 (3x3) | Optimized for automotive HMI applications, SSI output, wettable flanks |
| MA600A | 12-Bit to 15-Bit | SPI, ABZ, PWM, UVW, SSI | 3 to 3.6 | 7 | 20+ (No Upper Limit) | 75 to 17k | 0 | -40 to +125 | QFN-16 (3x3) | TMR front-end high accuracy and BW, 0.6° INL (<0.1° INL through user calibration w/ 32-word lookup table) |
| MAQ600A | 12-Bit to 15-Bit | SPI, ABZ, PWM, UVW, SSI | 3 to 3.6 | 7 | 20+ (No Upper Limit) | 75 to 17k | 0 | -40 to +125 | QFN-16 (3x3) | AEC-Q100, TMR front-end, high accuracy and BW, 0.6° INL (<0.1° INL through user calibration w/ 32-word lookup table) |

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